

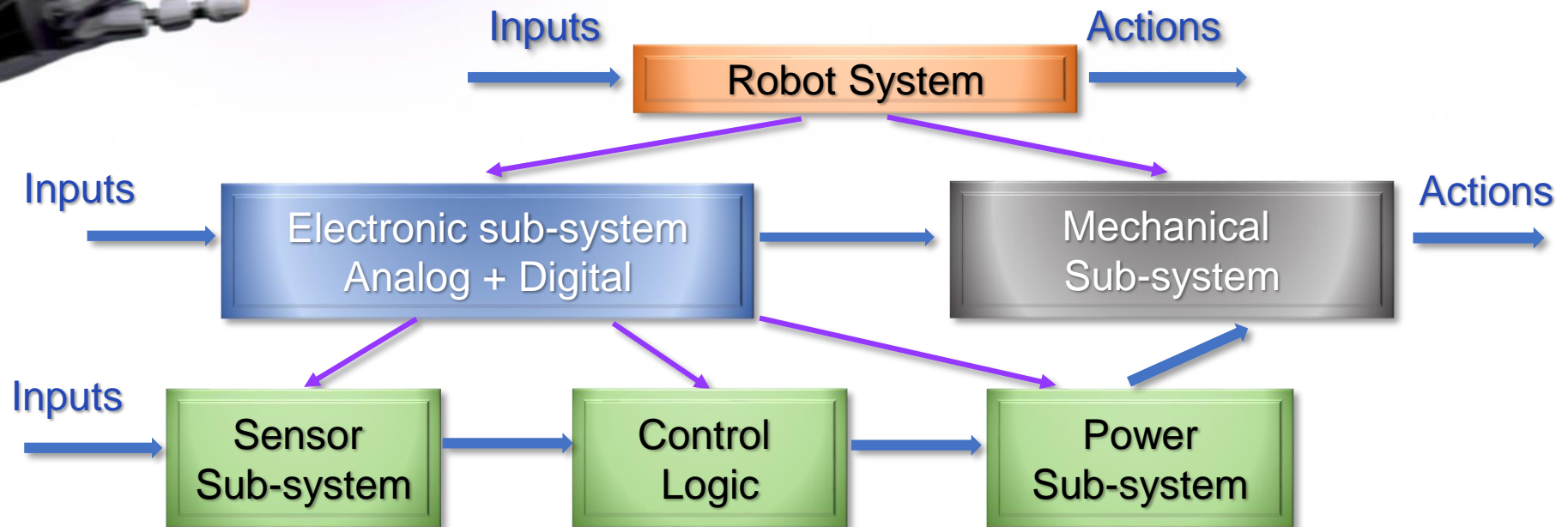
A futuristic robot arm, white and black, reaches out from the left side of the frame. The background is a composite image featuring a series of server racks on the right, a DNA double helix on the left, and a purple circular pattern in the center. The text "ELEC1100: Introduction to Electro-Robot Design" is overlaid on the purple circle.

ELEC1100: Introduction to Electro-Robot Design

Lecture 4: DC Power Sources and Regulation



ELEC1100 ROADMAP



Basic electronics:

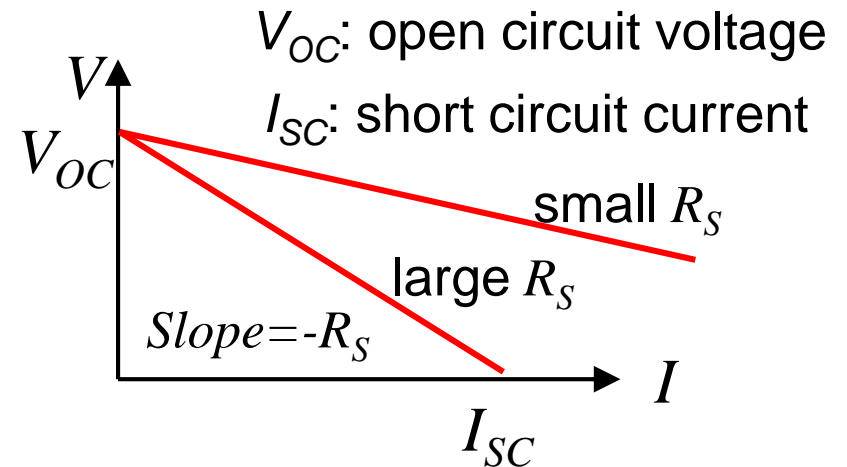
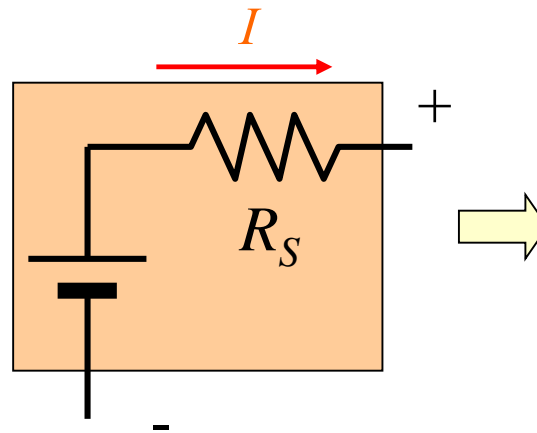
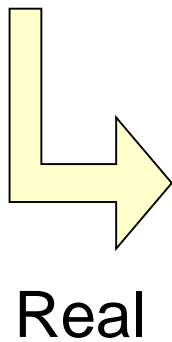
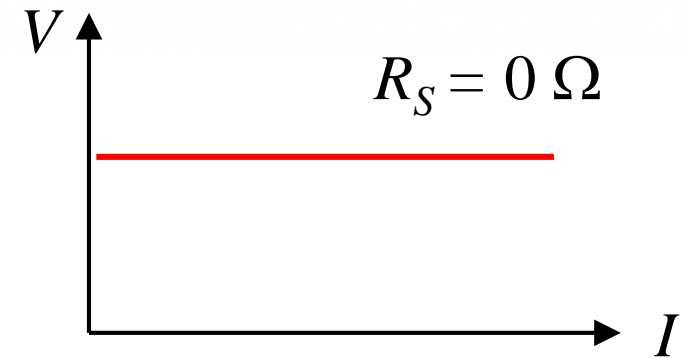
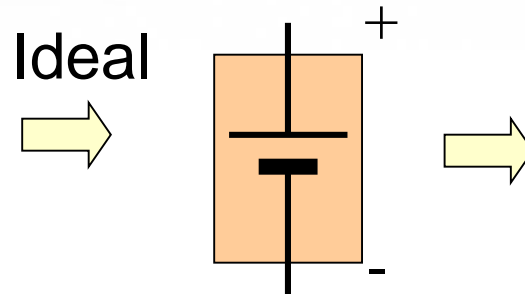
Wk1: Basic Electronics -
Charge/Current/Voltage/Resistor

Wk2: Energy/Power and DC Sources

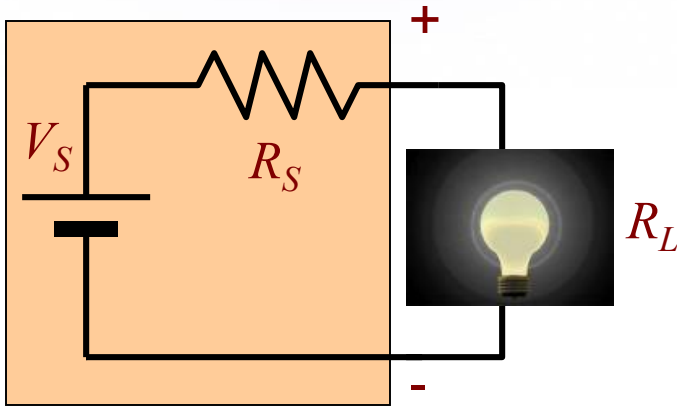




IDEAL AND NON-IDEAL BATTERY



POWER EFFICIENCY [1]



Current through the circuit: $I = \frac{V_S}{R_S + R_L}$

$$P_S = R_S \left(\frac{V_S}{R_S + R_L} \right)^2 \quad \text{Power consumed by } R_S$$

$$P_L = R_L \left(\frac{V_S}{R_S + R_L} \right)^2 \quad \text{Power consumed by } R_L$$

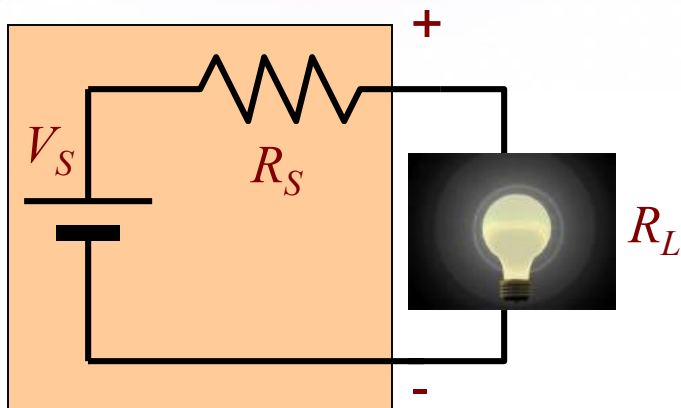
❖ To maximize P_L , we take the derivative of P_L with respect to R_L

$$\frac{d(P_L)}{d(R_L)} = \frac{d \left(\frac{V_S^2}{(R_S + R_L)^2} R_L \right)}{d(R_L)} = V_S^2 \cdot \frac{(R_S + R_L)^2 - R_L(2R_S + 2R_L)}{(R_S + R_L)^4}$$

Let $\frac{d(P_L)}{d(R_L)} = 0 \Rightarrow (R_S + R_L)^2 - R_L(2R_S + 2R_L) = 0 \Rightarrow R_S^2 - R_L^2 = 0 \Rightarrow R_S = R_L$



POWER EFFICIENCY [2]



Current through the circuit: $I = \frac{V_S}{R_S + R_L}$

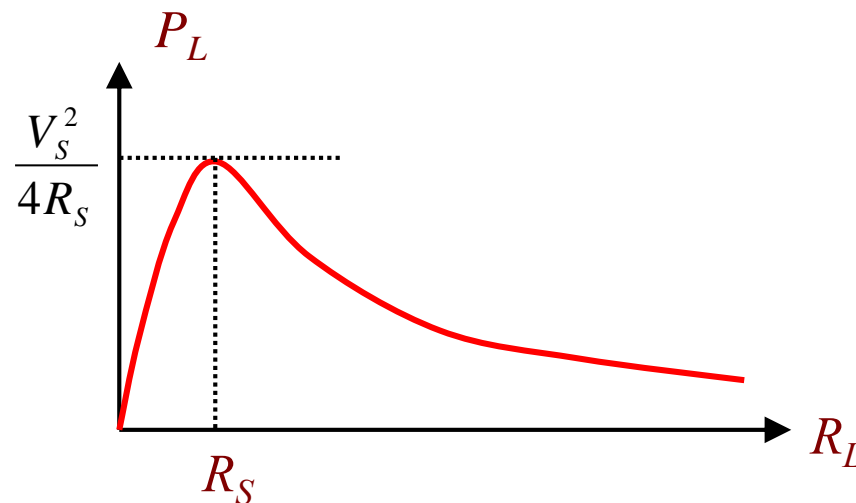
$$P_S = R_S \left(\frac{V_S}{R_S + R_L} \right)^2 \quad \text{Power consumed by } R_S$$

$$P_L = R_L \left(\frac{V_S}{R_S + R_L} \right)^2 \quad \text{Power consumed by } R_L$$

❖ Observation

➤ maximum deliverable power occurs when $R_S = R_L$

➤ maximum $P_L = \frac{V_S^2}{4R_S}$

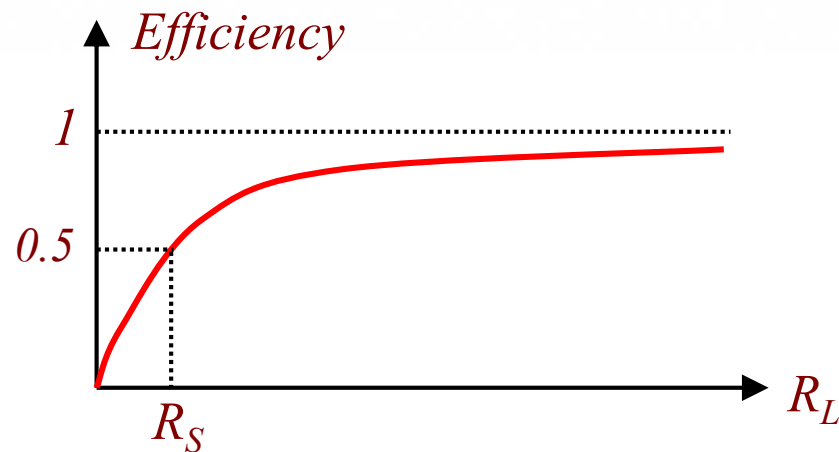




POWER EFFICIENCY [3]

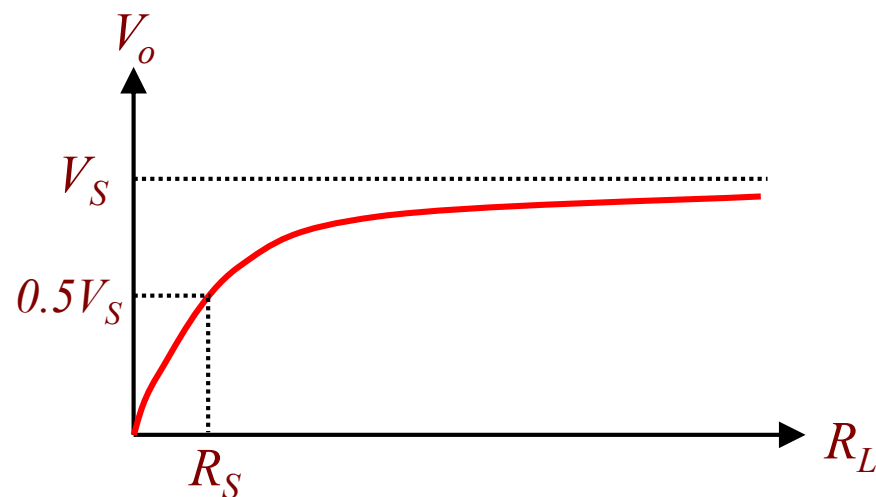
❖ Max efficiency

$$\begin{aligned}\text{efficiency} &= \frac{P_L}{P_L + P_S} = \frac{I^2 \cdot R_L}{I^2 \cdot R_L + I^2 \cdot R_S} \\ &= \frac{R_L}{R_L + R_S} = \frac{1}{1 + \frac{R_S}{R_L}}\end{aligned}$$



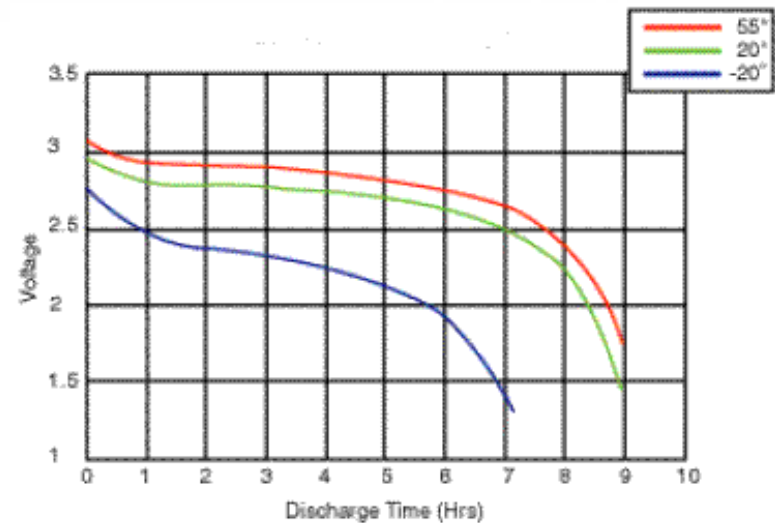
❖ The output voltage versus R_L

$$V_o = V_L = V_S \cdot \frac{R_L}{R_L + R_S} = V_S \cdot \left(\frac{1}{1 + \frac{R_S}{R_L}} \right)$$



BATTERY CHARACTERISTICS

- ❖ Battery voltage is not constant



Li battery characteristics at different temperature versus time

- ❖ Need to stabilize the voltage to provide predictable performance



BATTERY TYPES

Primary Battery	Voltage	Energy (MJ/kg)	Remarks
Zinc chloride/carbon	1.5V	0.13	Inexpensive
Alkaline	1.5V	0.4-0.59	Most commonly used
Silver oxide	1.55V	0.47	Very expensive, only used in button cells
Lithium manganese dioxide	3.0V	0.83-1.01	Expensive and slow discharge For high drain usage only
Mercury oxide	1.35V	0.5	Constant voltage, but banned in most countries because of health concerns

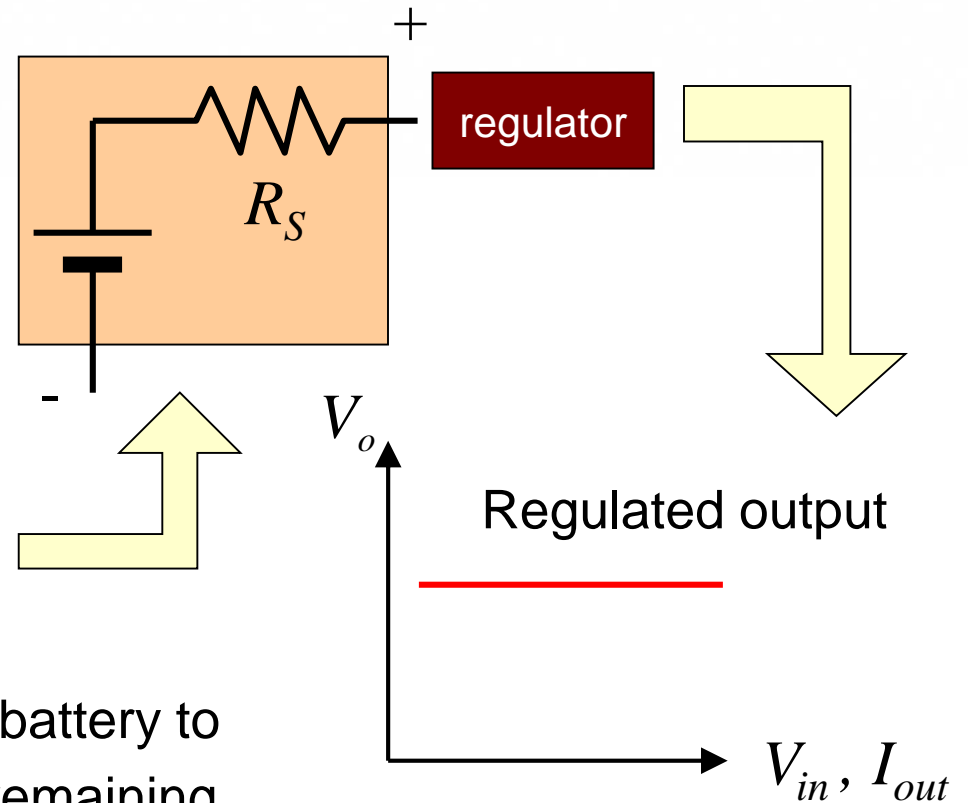
Rechargeable	Voltage	Energy (MJ/kg)	Remarks
NiCd	1.2V	0.14	Inexpensive, but with “memory” effect
Lead–acid	2.1V	0.14	High discharge rate and environmental hazard
NiMH	1.2V	0.36	Heavy and high discharge rate
NiZn	1.6V	0.36	Newly introduced in 2009 and limited size only
Lithium ion	3.6V	0.46	Low discharge and volatile (explode if short circuit)





REGULATED OUTPUT

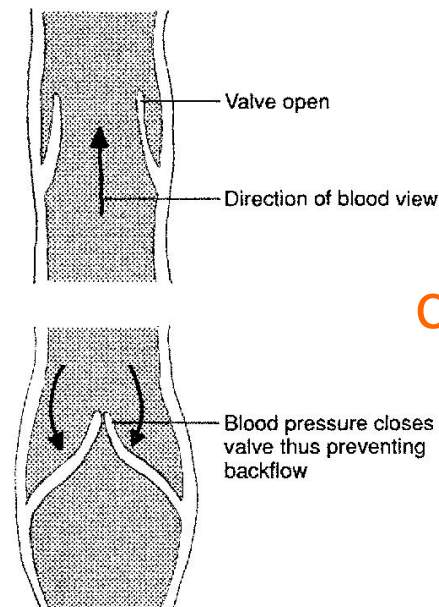
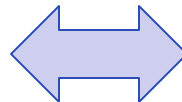
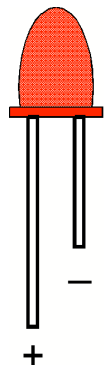
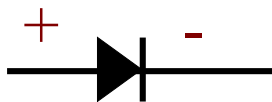
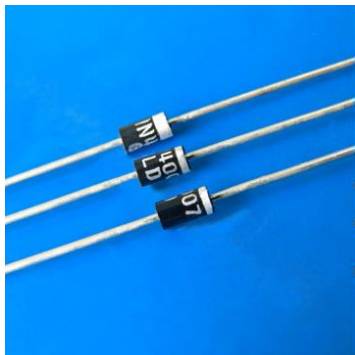
- ❖ Most battery-operated systems need a regulator to provide a constant voltage
- ❖ Regulators can also provide different voltages to different parts of a system
- ❖ Example: you will use **12V** from the battery to drive the motor and **5V** to drive the remaining circuits



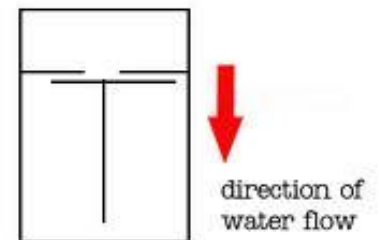


DIODE

- ❖ A diode is a device that only allows current to flow in one direction (e.g. LED)
- ❖ Symbol and characteristics



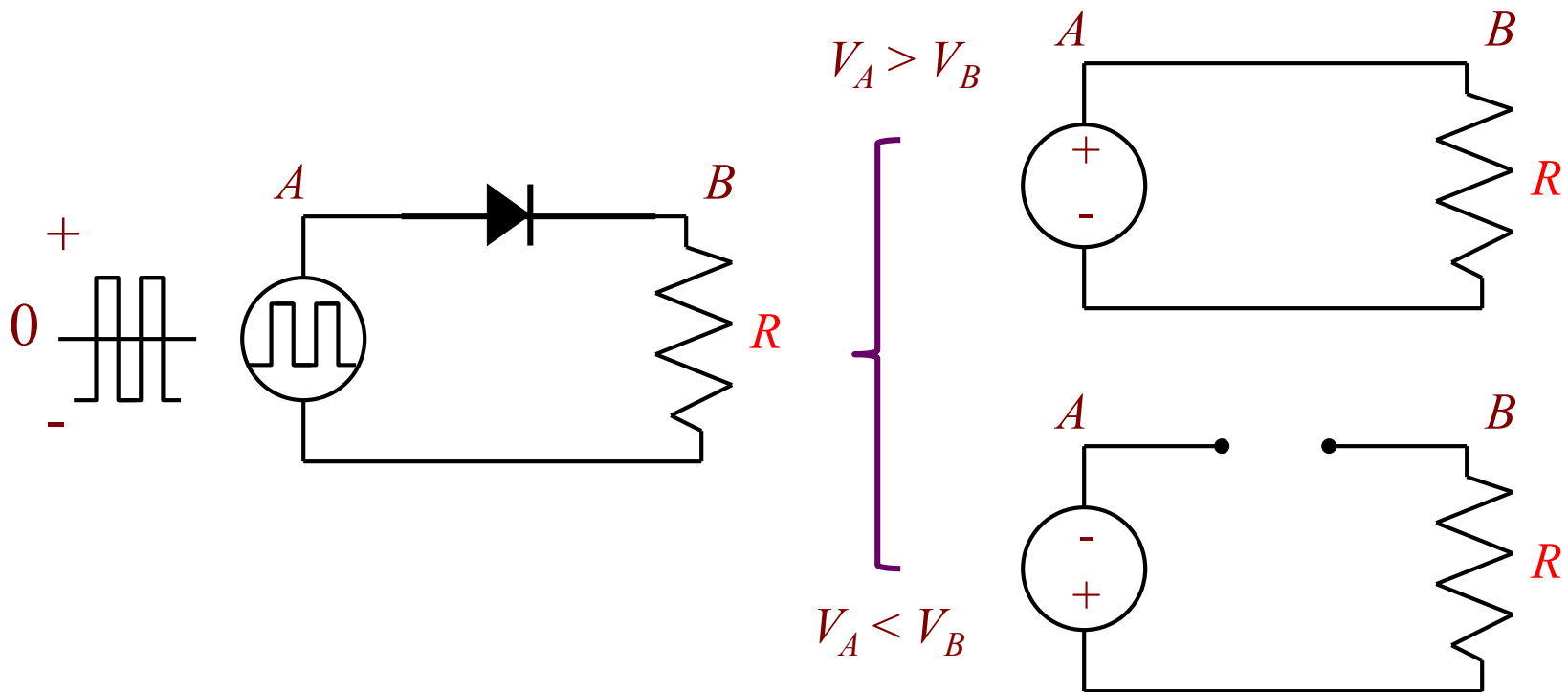
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DIODE EQUIVALENT CIRCUIT

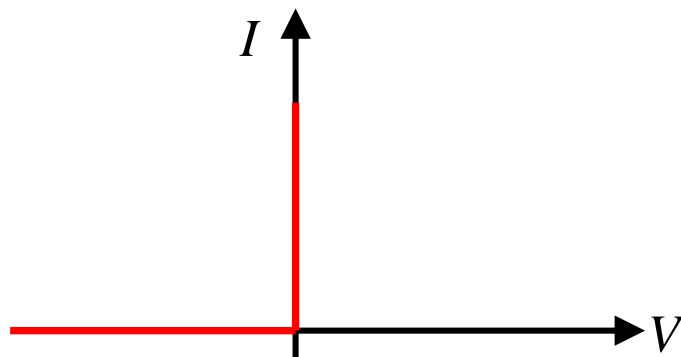
- ❖ A diode becomes a short circuit under forward bias and open circuit when reverse biased



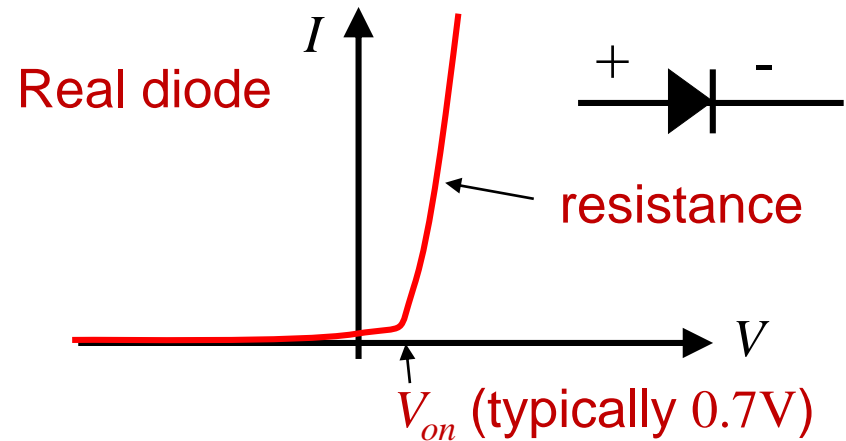


DESCRIPTION OF DIODE CHARACTERISTICS

- ❖ I-V characteristics of a typical diode



I-V curve for an ideal diode

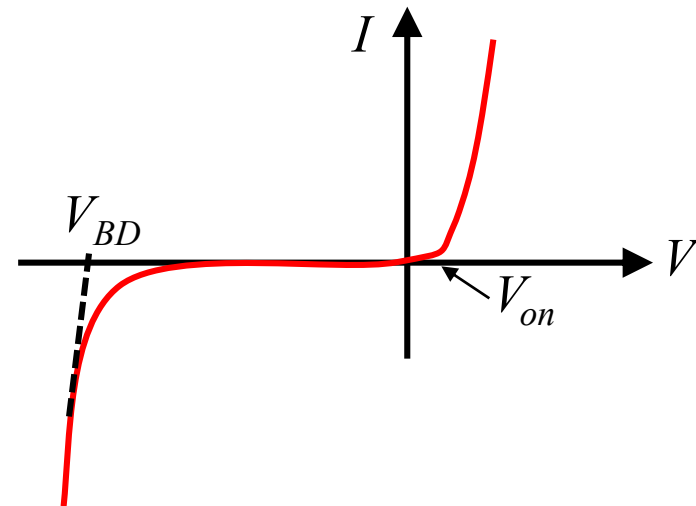
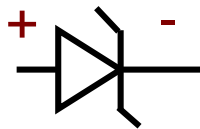


- ❖ At reverse voltage, current is **zero** (no current)
- ❖ At forward voltage, current is **infinite** (or any current)



ZENER DIODE

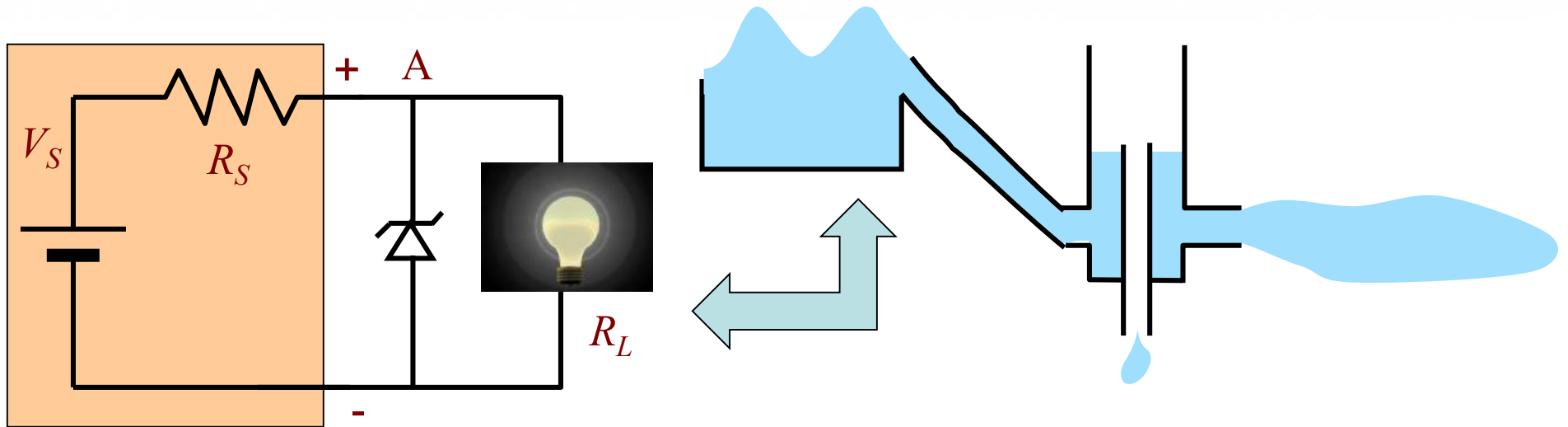
- ❖ Similar to a diode, but it also allows current to flow when reverse voltage is larger than a certain value
- ❖ Symbol and characteristics



- ❖ Allow conduction when $V < V_{BD}$ or $V > V_{on}$
- ❖ Typical value $V_{BD} = -5.7 \text{ V}$ or $V_{on} = 0.7 \text{ V}$

CONNECTING A ZENER DIODE

- ❖ Circuit construction with Zener diodes



- ❖ When $V_A > |V_{BD}|$, the Zener diode will clamp the voltage to V_{BD} to protect the circuit.
- ❖ Problem: power waste

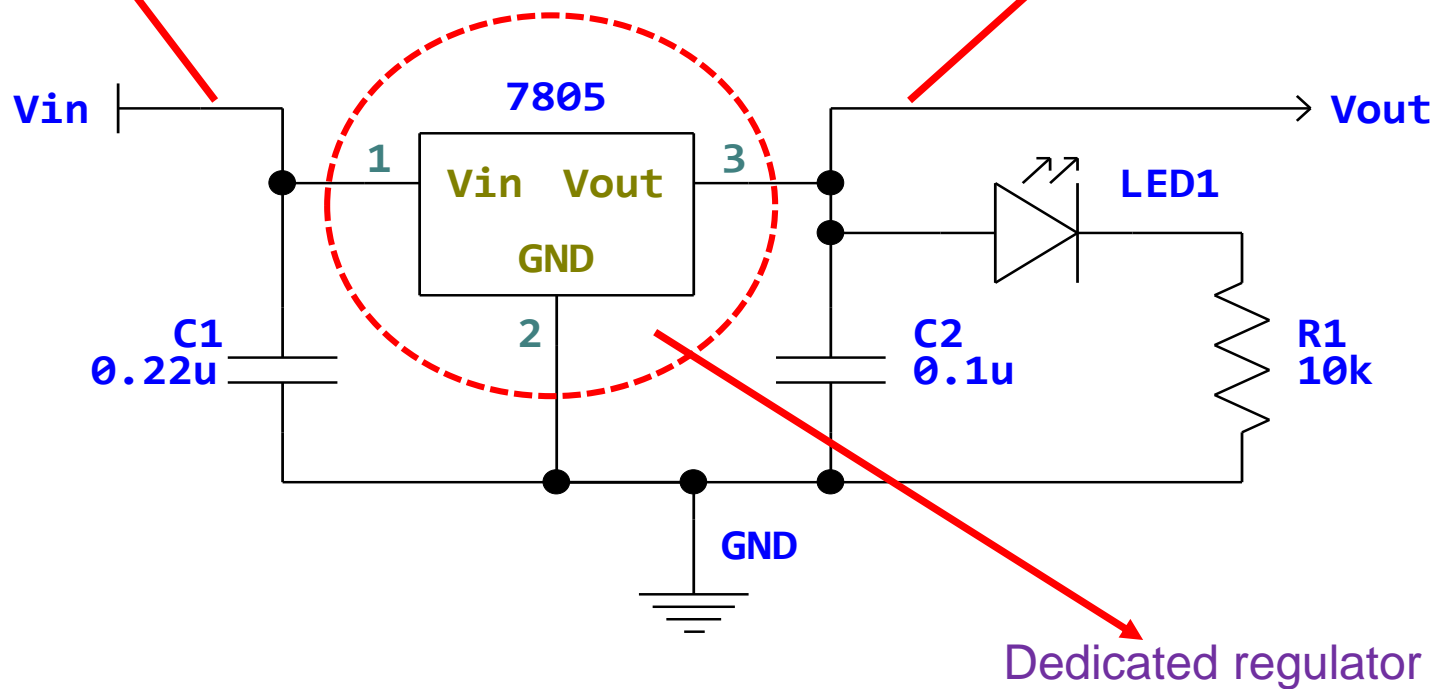


DEDICATED VOLTAGE REGULATOR

❖ In your Lab#02:

High voltage for motor drivers

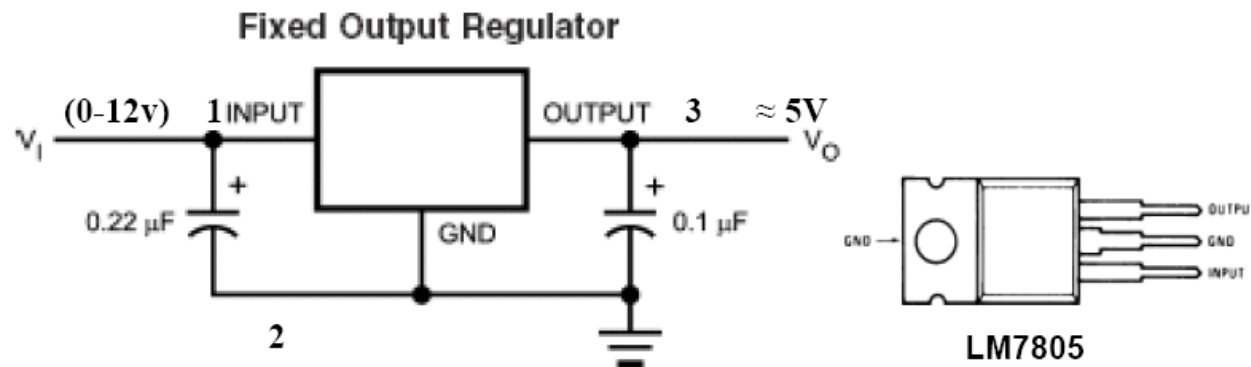
Low voltage for ICs





LM7805

- ❖ It is the Integrated Circuit (IC) to be used in your lab



- ❖ No need to understand the internal circuit (as you need to take more advanced courses)
- ❖ Only IC Function knowledge is needed
- ❖ A capacitor is commonly used to stabilize the input



MEASURE OF A REGULATOR PERFORMANCE

❖ Line regulation

- It measures how stable the output voltage is with respect to the change of the input voltage

$$\text{Line regulation} = \frac{\Delta V_o}{\Delta V_I}$$

- Ideally, it is equal to zero

❖ Load regulation

- It measures how stable the output voltage is with respect to the change of output current

$$\text{Load regulation} = \frac{\Delta V_o}{\Delta I_o}$$

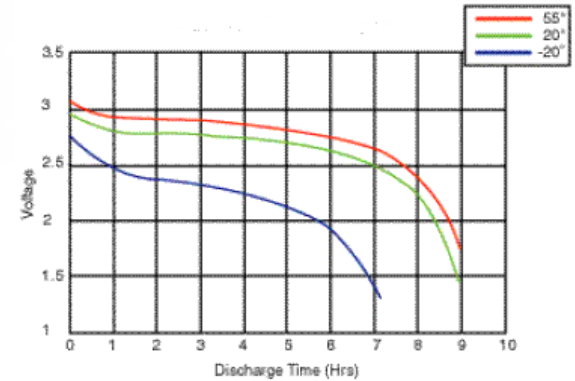
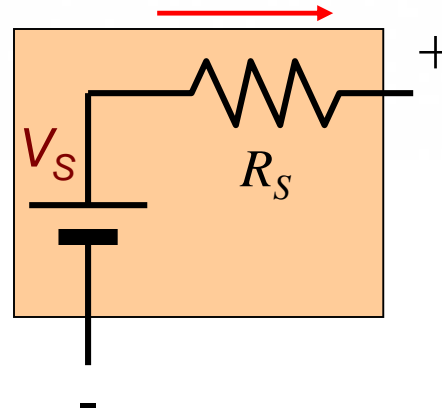
- Ideally, it is equal to zero





LECTURE SUMMARY

- ❖ Battery characteristics



- ❖ New element learned

Diode



- ❖ The importance of voltage regulation
- ❖ LM7805 voltage regulator





NEXT LECTURE

- ❖ Integrated circuits
- ❖ Pulse generation



QUESTIONS?

